

Calibration, falsifiability and Macau

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My message in one slide

- Setting: On-line decision making
(*aka adversarial data or robust time series*)
- Goal: Use economic forecasts for decision making

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Take Aways

crazy-Calibration + low-regret \implies low-macau \implies good decisions

Prove the Earth is round!

- Fun question: What personal evidence do you have that the earth is round?

Prove the Earth is round!

- Fun question: What personal evidence do you have that the earth is round?
- Can you prove it is round? NO!
- But, you can make claims that could easily be shown wrong.
- Called falsifiability

Operationalizing falsifiability

- We will falsify someone's claim by winning bets placed against them
- Claim: $\hat{Y} \approx EY$
 - Prove it wrong by winning lots of money:

$$\text{expected winnings} = E \left(B (Y - \hat{Y}) \right)$$

- $(Y - \hat{Y})$ is a "fair" bet
- B is amount bet

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$$E(B(Y - \hat{Y}))$$

(Start with bet B)

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- $(Y - \hat{Y})$ is a "fair" bet
 - B is amount bet
- How to avoid being proven wrong by:

$$\text{Macau} \equiv \max_{|B| \leq 1} E \left(B (Y - \hat{Y}) \right)$$

(worry about worst bet)

Operationalizing falsifiability

- We will falsify someone's claim by winning bets placed against them
- Claim: $\hat{Y} \approx EY$
 - Prove it wrong by winning lots of money:

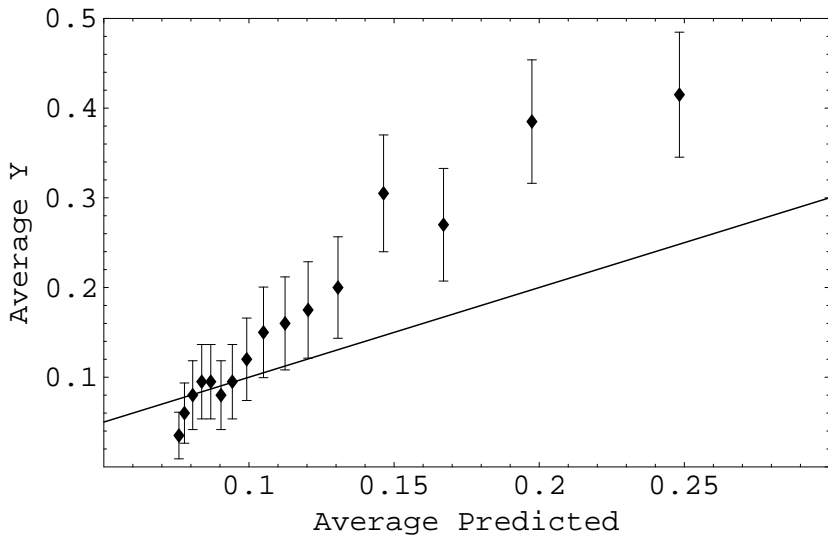
$$\text{expected winnings} = E \left(B (Y - \hat{Y}) \right)$$

- $(Y - \hat{Y})$ is a "fair" bet
 - B is amount bet
- How to avoid being proven wrong by:

$$\min_{\hat{Y}} \max_{|B| \leq 1} E \left(B (Y - \hat{Y}) \right)$$

(mini-max)

On to calibration



Crazy calibration variable

Y	X_1	X_2	X_3	X_4
Y_1	X_{11}	X_{12}	X_{13}	X_{14}
Y_2	X_{21}	X_{22}	X_{23}	X_{24}
Y_3	X_{31}	X_{32}	X_{33}	X_{34}
Y_4	X_{41}	X_{42}	X_{43}	X_{44}
\vdots	\vdots	\vdots	\vdots	\vdots
Y_t	X_{t1}	X_{t2}	X_{t3}	X_{t4}

Starting with our data that we observed up to time t

Crazy calibration variable

Y	X_1	X_2	X_3	X_4
Y_1	X_{11}	X_{12}	X_{13}	X_{14}
Y_2	X_{21}	X_{22}	X_{23}	X_{24}
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Y_t	X_{t1}	X_{t2}	X_{t3}	X_{t4}

$$\hat{\beta}_t = \arg \min_{\beta} \sum_{i=1}^t (Y_i - \beta' X_i)^2$$

We can fit $\hat{\beta}_t$ on everything up to time t

Crazy calibration variable

Y	X_1	X_2	X_3	X_4
Y_1	X_{11}	X_{12}	X_{13}	X_{14}
Y_2	X_{21}	X_{22}	X_{23}	X_{24}
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Y_t	X_{t1}	X_{t2}	X_{t3}	X_{t4}

$$X_{t+1,1} \quad X_{t+1,2} \quad X_{t+1,3} \quad X_{t+1,4} \quad \hat{\beta}_t$$

$$\hat{Y}_{t+1} = \hat{\beta}_t' X_{t+1}$$

From a new X_{t+1} we can compute \hat{Y}_{t+1}

Crazy calibration variable

Y	X_1	X_2	X_3	X_4	$\hat{\beta}$
Y_1	X_{11}	X_{12}	X_{13}	X_{14}	0
Y_2	X_{21}	X_{22}	X_{23}	X_{24}	$\hat{\beta}_1$
Y_3	X_{31}	X_{32}	X_{33}	X_{34}	$\hat{\beta}_2$
Y_4	X_{41}	X_{42}	X_{43}	X_{44}	$\hat{\beta}_3$
\vdots	\vdots	\vdots	\vdots	\vdots	\vdots
Y_t	X_{t1}	X_{t2}	X_{t3}	X_{t4}	$\hat{\beta}_{t-1}$

Looking at only the first part of the data, we can generate:

$$\hat{\beta}_0, \hat{\beta}_1, \hat{\beta}_2, \hat{\beta}_3, \hat{\beta}_4, \dots, \hat{\beta}_{t-1}$$

Crazy calibration variable

Y	X_1	X_2	X_3	X_4	$\hat{\beta}$	\hat{Y}
Y_1	X_{11}	X_{12}	X_{13}	X_{14}	0	$\hat{Y}_1 = 0$
Y_2	X_{21}	X_{22}	X_{23}	X_{24}	$\hat{\beta}_1$	$\hat{Y}_2 = \hat{\beta}'_1 X_2$
Y_3	X_{31}	X_{32}	X_{33}	X_{34}	$\hat{\beta}_2$	$\hat{Y}_3 = \hat{\beta}'_2 X_3$
Y_4	X_{41}	X_{42}	X_{43}	X_{44}	$\hat{\beta}_3$	$\hat{Y}_4 = \hat{\beta}'_3 X_4$
\vdots	\vdots	\vdots	\vdots	\vdots	\vdots	\vdots
Y_t	X_{t1}	X_{t2}	X_{t3}	X_{t4}	$\hat{\beta}_{t-1}$	$\hat{Y}_t = \hat{\beta}'_{t-1} X_t$

Each of these leads to a next round

$$\hat{Y}_1, \hat{Y}_2, \hat{Y}_3, \hat{Y}_4, \dots, \hat{Y}_t$$

Crazy calibration variable

Y	X_1	X_2	X_3	X_4	$\hat{\beta}$	\hat{Y}
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\vdots	\vdots	\vdots	\vdots	\vdots	\vdots	\vdots
Y_t	X_{t1}	X_{t2}	X_{t3}	X_{t4}	$\hat{\beta}_{t-1}$	$\hat{Y}_t = \hat{\beta}'_{t-1} X_t$

Theorem (Foster 1991, Forster 1999)

Such an on-line least squares forecast generates low regret:

$$\sum_{t=1}^T (Y_t - \hat{Y}_t)^2 - \min_{\beta} \sum_{t=1}^T (Y_t - \beta' X_t)^2 \leq O(\log(T))$$

Crazy calibration variable

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Works no matter what the X's are.

Crazy calibration variable

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Y_t	X_{t1}	X_{t2}	\hat{Y}_t	X_{t4}	$\hat{\beta}_{t-1}$	$\hat{Y}_t = \hat{\beta}'_{t-1} X_t$

Even if one of the X 's were \hat{Y} !

Crazy calibration variable

Y	X_1	X_2	X_3	X_4	$\hat{\beta}$	\hat{Y}
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Theorem (\implies Foster and Kakade 2008, Foster and Hart 2018)

Adding the crazy calibration variable generates low macau:

$$(\forall i) \sum_{t=1}^T X_{t,i} (Y_t - \hat{Y}_t) = O(\sqrt{T \log(T)})$$

Macau as the “normal equation”

$E(Y X)$	Least squares	Normal equations
Statistics	$\min_{\beta} \sum (Y_i - \beta \cdot X_i)^2$	$\sum X_i (Y_i - \beta \cdot X_i) = 0$

The normal equation is the same as:

$$\max_{\alpha} \sum_i \alpha' X_i (Y_i - \beta' X_i) = 0$$

Which is solved by the β minimizer:

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Probability	$\min_f E((Y - \underbrace{f(X)}_{\text{aka } E(Y X)})^2)$	$(\forall g) E(g(X) (Y - f(X))) = 0$

The normal equation is the same as:

$$\max_g E(g(X)(Y - f(X))) = 0$$

Which is solved by the $f(\cdot)$ minimizer:

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online	low regret	low macau

$$\text{Regret} \equiv \sum_{t=1}^T (Y_t - \hat{Y}_t)^2 - \min_{\beta} \sum_{t=1}^T (Y_t - \beta \cdot X_t)^2$$

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$$\text{Macau} \equiv \max_{\alpha: |\alpha| \leq 1} \sum_{t=1}^T \alpha \cdot X_t (Y_t - \hat{Y}_t)$$

Macau as the “normal equation”

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- statistics: Least squares \iff normal equations
- probability: Least squares \iff normal equations

Macau as the “normal equation”

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Take Aways

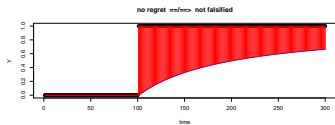
on-line low regret \Leftrightarrow *on-line low macau*

low regret $\not\Rightarrow$ low macau

No regret $\not\Rightarrow$ not falsified

t	1	2	3	4	...	$T-1$	T	$T+1$	$T+2$	$T+3$...	$3T$
Y_t	0	0	0	0	...	0	1	1	1	1	...	1
X_t	1	1	1	1	...	1	1	1	1	1	...	1
\hat{Y}_t	0	0	0	0	...	0	0	$\frac{1}{T}$	$\frac{2}{T+1}$	$\frac{3}{T+2}$...	$\frac{2}{3}$

How about a bet?



Not falsified $\not\Rightarrow$ no regret

t	1	2	3	4	...	T	$T+1$...
Y_t	0	1	0	1	...	0	1	...
X_t	1	1	1	1	...	1	1	...
\hat{Y}_t	.6	.4	.6	.46	.4	...

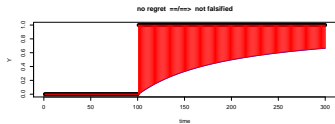
- Macau is zero
- Regret is $T/9$
- So: low macau \Rightarrow low regret

low regret $\not\Rightarrow$ low macau

No regret $\not\Rightarrow$ not falsified

t	1	2	3	4	...	$T-1$	T	$T+1$	$T+2$	$T+3$...	$3T$
Y_t	0	0	0	0	...	0	1	1	1	1	...	1
X_t	1	1	1	1	...	1	1	1	1	1	...	1
\hat{Y}_t	0	0	0	0	...	0	0	$\frac{1}{T}$	$\frac{2}{T+1}$	$\frac{3}{T+2}$...	$\frac{2}{3}$

How about a bet?



Not falsified $\not\Rightarrow$ no regret

t	1	2	3	4	...	T	$T+1$...
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(Skipping these proofs)

- Action A makes X dollars, action B makes Y dollars
 - We want forecasts that are close to X and Y
 - We want to be close on average
 - We will use least squares to estimate X and Y
- But, we want to take actions
- Will good estimates of X and Y lead to good decisions about A vs B ?

Contextual Bandits

Some notation:

a = action taken $\in \mathfrak{R}^k$ (eg inventory levels)

X_t = Context at time t

a_t^* = best action at time t

$r_t(a)$ = Reward at time t playing a

$V_t^* = \max_a E(r_t(a)|X_t) = E(r_t(a^*)|X_t)$

$\underline{q}_t(a) \leq E(r_t(a)|X_t) \leq \bar{q}_t(a)$

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What are good falsifiable claims about a^* ?

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Too precise:

“Here are two bounding functions \underline{q} and \bar{q} :

- $\underline{q}_t(a) = \bar{q}_t(a)$ ”

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Too loose:

- “Here is a_t^* .”

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$\underline{q}_t(a) \leq E(r_t(a)|X_t) \leq \bar{q}_t(a)$

Just right:

“Here is a target V^* and approximating quadratics around a^* :

- $\bar{q}_t(a) = V_t^* - q\|a - a_t^*\|^2$
- $\bar{q}_t(a) - \underline{q}_t(a) = \Delta\|a - a_t^*\|^2$ ”

Why is low macau useful?

$$C(a) = \sum_{t=1}^T c_t(a) \quad a^* \equiv \arg \min_a C(a)$$

- Supposed each $c_t(\cdot)$ is convex
- Goal: play a to minimize $C(a)$
- Eg: We could use SGD on $\nabla c_t(\cdot)$
- called “on-line convex optimization” with regret:

$$\text{regret} \equiv \sum_{t=1}^T (c_t(\hat{a}_t) - c_t(a^*))$$

Why is low macau useful?

$$C(a) = \sum_{t=1}^T c_t(a) \quad a^* \equiv \arg \min_a C(a)$$

The regret is bounded by the gradient:

$$\begin{aligned} \text{regret} &= \sum_{t=1}^T (c_t(\hat{a}_t) - c_t(a^*)) \\ &\leq \sum_{t=1}^T (\hat{a}_t - a^*) \cdot \nabla c_t(\hat{a}_t) \end{aligned}$$

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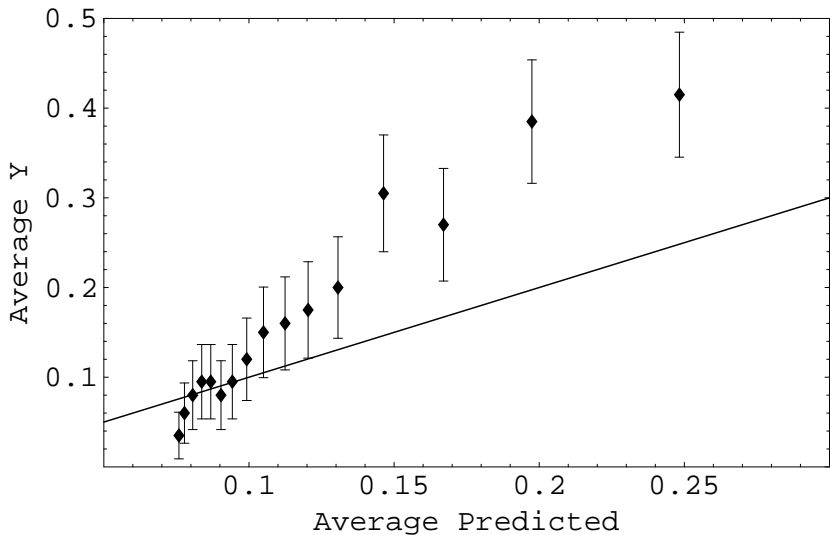
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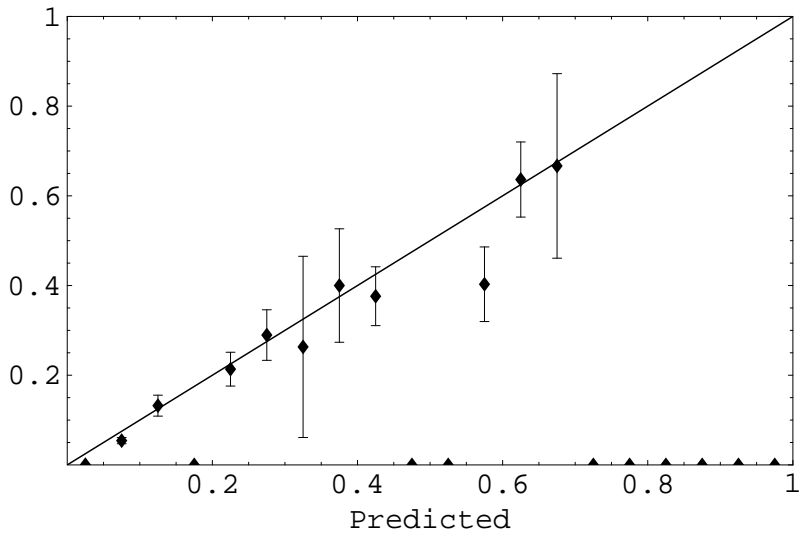
The regret is bounded by the gradient:

$$\begin{aligned} \text{regret} &= \sum_{t=1}^T (c_t(\hat{a}_t) - c_t(a^*)) \\ &\leq \sum_{t=1}^T (\hat{a}_t - a^*) \cdot \nabla c_t(\hat{a}_t) \\ &= \sum_{t=1}^T (\hat{a}_t - a^*) \cdot \left(\nabla c_t(\hat{a}_t) - \widehat{\nabla c_t}(\hat{a}_t) \right) + (\hat{a}_t - a^*) \cdot \widehat{\nabla c_t}(\hat{a}_t) \\ \text{regret} &\leq \text{macau} \end{aligned}$$

without crazy-calibration variable



Using the crazy-calibration variable



Calibration Theorem

Theorem (\implies F. and Kakade 2008, \impliedby new)

Let R be the quadratic regret of a forecast \hat{Y}_t against a linear regression on X_t . Let M be the Macau of \hat{Y}_t using linear functions of X_t to create falsifying bets. Then if $\hat{Y}_t = [X_t]_0$, we have $R = o(T)$ iff $M = o(T)$.

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Note: Typically, $R = O(\log(T))$ iff $M = \tilde{O}(\sqrt{T})$ for the actual algorithms I know.

(Sasha Rakhlin and Dylan Foster have a proof for IID.)

Calibration Theorem

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Let R be the quadratic regret of a forecast \hat{Y}_t against a linear regression on X_t . Let M be the Macau of \hat{Y}_t using linear functions of X_t to create falsifying bets. Then if $\hat{Y}_t = [X_t]_0$, we have $R = o(T)$ iff $M = o(T)$.

Proof sketch: Consider the forecasts $(1 - w)\hat{Y}_t + w\alpha \cdot X_t$ for the any α . Let $Q(w)$ be the total quadratic error of this family of forecast. The following are equivalent:

- $Q(0) \leq Q(w)$ (No regret condition)
- $Q'(0)$ is zero. (No macau condition)

Recipe for good decisions

- List bets that you would make to show \hat{a}_t is not optimal
- Convert these to regression variables
- Add the crazy-calibration variable
- Run a low regret least squares algorithm
- Make decision based on this forecast

What bets to place?

	Bet
convex	$[\hat{a}_t - a^*]_i$
experts	$e_{a^*} - e_{\hat{a}_t}$
internal regret	$(e_a - e_b)I_{\hat{a}_t=b}$
bandits	$\frac{I_{a_t=a}}{P(a_t=a)} - \frac{I_{a_t=\hat{a}_t}}{P(a_t=\hat{a}_t)}$
contextual	$X_t \times \left(\frac{I_{a_t=a}}{P(a_t=a)} - \frac{I_{a_t=\hat{a}_t}}{P(a_t=\hat{a}_t)} \right)$
continuous	$(a_t - Mx_t)^2$
LQR	$(a_t - \sum_{i=1}^{\log T} M_i x_{t-i})^2$
reinforcement Learning	TD learn

What bets to place?

	Bet	dimension
convex	$[\hat{a}_t - a^*]_i$	$\in \mathbb{R}^d$
experts	$e_{a^*} - e_{\hat{a}_t}$	$\in \mathbb{R}^k$
internal regret	$(e_a - e_b)I_{\hat{a}_t=b}$	$\in \mathbb{R}^{k^2}$
bandits	$\frac{I_{a_t=a}}{P(a_t=a)} - \frac{I_{a_t=\hat{a}_t}}{P(a_t=\hat{a}_t)}$	$\in \mathbb{R}^k$
contextual	$X_t \times \left(\frac{I_{a_t=a}}{P(a_t=a)} - \frac{I_{a_t=\hat{a}_t}}{P(a_t=\hat{a}_t)} \right)$	$\in \mathbb{R}^{dk}$
continuous	$(a_t - Mx_t)^2$	$\in \mathbb{R}^{dk}$
LQR	$(a_t - \sum_{i=1}^{\log T} M_i x_{t-i})^2$	$\in \mathbb{R}^{dk \log(T)}$
reinforcement Learning	TD learn	

Theorem (Dicker 2019)

Least squares plus the calibration variable generates an estimate of the RL value function with low Macau.

Theorem (Dicker 2019)

A tweaked version of TD learning with $1/\sqrt{T}$ rates generates an estimate of the RL value function with low Macau.

Theorem (Dicker 2019)

Least squares plus the calibration variable generates an estimate of the RL value function with low Macau.

Proof: Follows from F. and Kakade 2008.

Theorem (Dicker 2019)

A tweaked version of TD learning with $1/\sqrt{T}$ rates generates an estimate of the RL value function with low Macau.

Proof: Similar to Dicker and F. 2018.

Take Aways

crazy-Calibration + low-regret \iff *low-macau* \implies *good decisions*

Take Aways

crazy-Calibration + low-regret \iff *low-macau* \implies *good decisions*

Thanks!

Proofs by example:

- low Regret $\not\Rightarrow$ low Macau
- low Regret \Leftarrow low Macau

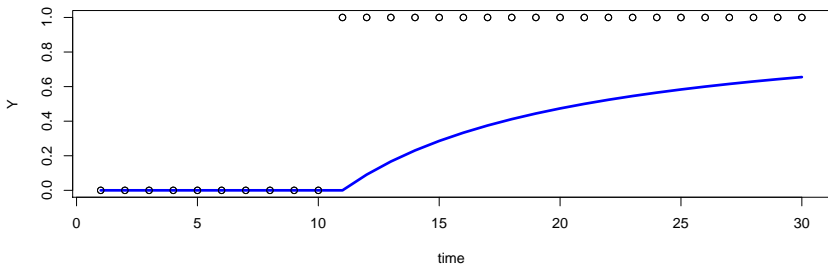
Bets:

- Experts
- No Internal Regret
- Bandits, (scalar version), (exploration).
- Contextual Bandits
- Continuous action contextual Bandits
- Convex optimization, (one point), ($1/T$ with smooth)
- Reinforcement Learning
- LQR

No regret $\not\Rightarrow$ not falsified

t	1	2	3	4	...	$T-1$	T	$T+1$	$T+2$	$T+3$...	$3T$
Y_t	0	0	0	0	...	0	1	1	1	1	...	1
X_t	1	1	1	1	...	1	1	1	1	1	...	1
\hat{Y}_t	0	0	0	0	...	0	0	$\frac{1}{T}$	$\frac{2}{T+1}$	$\frac{3}{T+2}$...	$\frac{2}{3}$

no regret $\not\Rightarrow$ not falsified



No regret $\not\Rightarrow$ not falsified

t	1	2	3	4	...	$T-1$	T	$T+1$	$T+2$	$T+3$...	$3T$
Y_t	0	0	0	0	...	0	1	1	1	1	...	1
X_t	1	1	1	1	...	1	1	1	1	1	...	1
\hat{Y}_t	0	0	0	0	...	0	0	$\frac{1}{T}$	$\frac{2}{T+1}$	$\frac{3}{T+2}$...	$\frac{2}{3}$

On-line least squares suffers no-regret:

- β_t minimizes $\sum_{i=1}^t (Y_i - \beta \cdot X_t)^2$
- $\hat{Y}_t = \beta_{t-1} \cdot X_t$
- Total error: $\sum (Y_t - \hat{Y}_t)^2 = \min_{\beta} \sum (Y_t - \beta X_t)^2 + 4/9$
- In general, on-line least squares has $\log(T)$ total regret
- In this case, it actually wins by about $O(1)$.

No regret $\not\Rightarrow$ not falsified

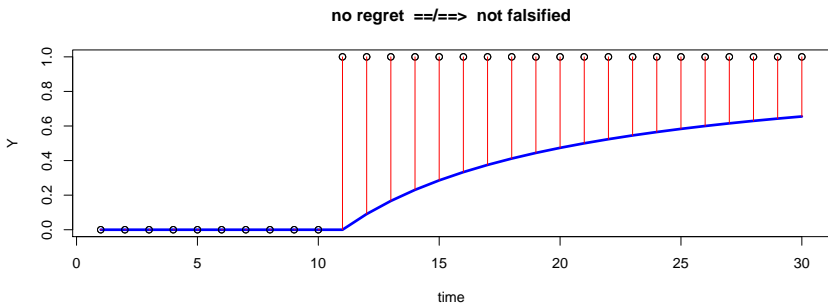
t	1	2	3	4	...	$T-1$	T	$T+1$	$T+2$	$T+3$...	$3T$
Y_t	0	0	0	0	...	0	1	1	1	1	...	1
X_t	1	1	1	1	...	1	1	1	1	1	...	1
\hat{Y}_t	0	0	0	0	...	0	0	$\frac{1}{T}$	$\frac{2}{T+1}$	$\frac{3}{T+2}$...	$\frac{2}{3}$

How about a bet?

No regret $\not\Rightarrow$ not falsified

t	1	2	3	4	...	$T-1$	T	$T+1$	$T+2$	$T+3$...	$3T$
Y_t	0	0	0	0	...	0	1	1	1	1	...	1
X_t	1	1	1	1	...	1	1	1	1	1	...	1
\hat{Y}_t	0	0	0	0	...	0	0	$\frac{1}{T}$	$\frac{2}{T+1}$	$\frac{3}{T+2}$...	$\frac{2}{3}$

How about a bet?



No regret $\not\Rightarrow$ not falsified

t	1	2	3	4	...	$T-1$	T	$T+1$	$T+2$	$T+3$...	$3T$
Y_t	0	0	0	0	...	0	1	1	1	1	...	1
X_t	1	1	1	1	...	1	1	1	1	1	...	1
\hat{Y}_t	0	0	0	0	...	0	0	$\frac{1}{T}$	$\frac{2}{T+1}$	$\frac{3}{T+2}$...	$\frac{2}{3}$

How about a bet?

- $Y_t > \hat{Y}_t$, so that is a safe bet!
- Construct this bet only using X_t

$$\sum_{i=1}^T X_t(Y - \hat{Y}_t) \approx T \frac{\log_e(3)}{2}$$

- Betting loses $\Omega(T)$

No regret $\not\Rightarrow$ not falsified

t	1	2	3	4	...	$T-1$	T	$T+1$	$T+2$	$T+3$...	$3T$
Y_t	0	0	0	0	...	0	1	1	1	1	...	1
X_t	1	1	1	1	...	1	1	1	1	1	...	1
\hat{Y}_t	0	0	0	0	...	0	0	$\frac{1}{T}$	$\frac{2}{T+1}$	$\frac{3}{T+2}$...	$\frac{2}{3}$

- Regret is $O(1)$
- Macau is $T/2$
- So: low regret $\not\Rightarrow$ low macau

Not falsified $\not\Rightarrow$ no regret

t	1	2	3	4	...	T	T+1	...
Y_t	0	1	0	1	...	0	1	...
X_t	1	1	1	1	...	1	1	...
\hat{Y}_t	.6	.4	.6	.46	.4	...

Not falsified $\not\Rightarrow$ no regret

t	1	2	3	4	...	T	T+1	...
Y_t	0	1	0	1	...	0	1	...
X_t	1	1	1	1	...	1	1	...
\hat{Y}_t	.6	.4	.6	.46	.4	...

Betting

- No bet based on X_t will win anything
- In other words,

$$\max_{\alpha} \sum_{i=1}^T \alpha \cdot X_t (Y - \hat{Y}_t) = 0$$

- This forecast is not falsified using linear functions of X_t

Not falsified $\not\Rightarrow$ no regret

t	1	2	3	4	...	T	$T+1$...
Y_t	0	1	0	1	...	0	1	...
X_t	1	1	1	1	...	1	1	...
\hat{Y}_t	.6	.4	.6	.46	.4	...

But, a better forecast exists

- $\sum(Y_t - \hat{Y}_t)^2 = .36T$
- $\min_{\beta}(Y_t - \beta X_t)^2 = .25T$
- Regret is $.11T$
- So, regret is $\Omega(T)$

Not falsified $\not\Rightarrow$ no regret

t	1	2	3	4	...	T	T+1	...
Y_t	0	1	0	1	...	0	1	...
X_t	1	1	1	1	...	1	1	...
\hat{Y}_t	.6	.4	.6	.46	.4	...

- Macau is zero
- Regret is $T/9$
- So: low macau $\not\Rightarrow$ low regret

Bet: Convex optimization (with gradients)

In the convex optimization problem, we observe a sequence of convex functions $c_t(\cdot)$. Our goal is to figure out an action \hat{x}_t^* to take at each point in time t to minimize $\sum_t c_t(\hat{x}_t^*)$.

- Forecast: Gradient of c_t at each point in time t
($g_t(x) \equiv \nabla c_t(x)$)
- Strategy: Pick a \hat{x}_t^* such that $\hat{g}_t(\hat{x}_t^*) = 0$.
- Worry: “The real optimum x^* would generate better performance.”
- Macau bets: $[x^* - \hat{x}_t^*]_i$ bet against $[g_t]_i - [\hat{g}_t]_i$

$$\text{Macau}_i = \sum_{t=1}^T [x^* - \hat{x}_t^*]_i ([g_t]_i - [\hat{g}_t]_i)$$

Bet: $[x^* - \hat{x}_t^*]_i$

Bet: Convex optimization (no gradients)

In the convex optimization problem, we observe a sequence of convex functions $c_t(\cdot)$. Our goal is to figure out an action \hat{x}_t^* to take at each point in time t to minimize $\sum_t c_t(\hat{x}_t^*)$.

- Forecast: $c_t(x)$ at points near \hat{x}_t^* , for example $x_t - \hat{x}_t^* \sim N(0, \sigma^2 I)$
- Strategy: Pick a \hat{x}_t^* to minimize $\hat{c}(\cdot)$
- Worry: “The real optimum x^* would generate better performance.”
- Macau bets: $(x^* - \hat{x}_t^*) \cdot (x_t - \hat{x}_t^*)$

$$\text{Macau} = \sum_{t=1}^T (x^* - \hat{x}_t^*) \cdot (x_t - \hat{x}_t^*) c(x)$$

Bet: $[x^* - \hat{x}_t^*]_i$

Bet: Optimizing continuous convex functions (with gradient)

Also assume each c_t is smooth, say $c_t \in \mathcal{C}_2$. We'll keep all else the same.

- We can use the macau to look at bets for how for $\hat{\beta}$ is from the best after the fact β
- Thus we know the optimum point is close to the best hind sight deciosion point (say $1/\sqrt{T}$ accuracy)
- This means the error in payoff space is $1/T$
- So it doesn't require a new algorithm or even new features

Bet: Experts

In the experts problem, we observe the payoff of k different experts. Our goal is to generate as much value as the best expert.

- Forecast: one value for each arm ($Y_t \in \mathbb{R}^k$, so $\hat{Y}_t \in \mathbb{R}^k$ also)
- Strategy: Pick arm with highest forecast ($\hat{a}_t = \arg \max_i [\hat{Y}_t]_i$)
- Worry: “Always playing arm b would generate more”
- Macau bet: $e_b = [0, 0, 0, \dots, 1, \dots, 0]'$

$$\text{Macau} = \max_{b \in \{1, \dots, k\}} \sum_t (e_b - e_{\hat{a}_t}) \cdot (Y_t - \hat{Y}_t)$$

Bet: $e_b - e_{\hat{a}_t}$

Bet: No Internal Regret

In the no-internal regret problem, we observe the payoff of k different experts. Our goal is to avoid feeling regret about possibly switching one of our actions to some other action.

- Forecast: one value for each expert ($Y_t \in \mathbb{R}^k$, so $\hat{Y}_t \in \mathbb{R}^k$ also)
- Strategy: Pick arm with highest forecast ($\hat{a}_t = \arg \max_j [\hat{Y}_t]_j$)
- Worry: “Playing c when we previously played b would have been better ($R^{c \rightarrow b} > 0$).”
- Macau bet:

$$(I_{\hat{a}_t=c}(e_b - e_c)) \cdot (Y_t - \hat{Y}_t)$$

Bet on $c \rightarrow b$: $I_{\hat{a}_t=c}(e_b - e_c)$

The rest isn't done yet!

Bet: Bandits (vector structure)

We only see outcomes on the one of k arms we pull.

- Forecast: Each arms payoff: $[Y_t]_i = \frac{r_t \mathbb{1}_{a_t=i}}{p(a_t=i)}$, so $\hat{Y}_t \in \mathfrak{R}^k$.
- Strategy: Pick arm with highest forecast ($\hat{a}_t = \arg \max_i [\hat{Y}_t]_i$) with some exploration also.
- Worry: Always playing b might have been better.
- Macau bet:

$$(e_b - e_{\hat{a}_t}) \cdot (Y_t - \hat{Y}_t)$$

Bet on b : $(e_b - e_{\hat{a}_t})$

Bet: Bandits (scalar version)

Play $a_t \in \{1, \dots, k\}$ and only see its outcome.

- Forecast: the arm actually played: $Y_t = \frac{r_t(a_t)}{p_t(a_t)}$, so $\hat{Y}_t(a_t) \in \mathfrak{R}$.
- Strategy: Pick arm with highest forecast ($\hat{a}_t = \arg \max_j \hat{Y}_t(j)$) with some exploration also.
- Worry: Always playing b might have been better.
- Macau bet:

$$\left(\frac{I_{a_t=b}}{p_t(b)} - \frac{I_{a_t=\hat{a}_t}}{p_t(\hat{a}_t)} \right) (Y_t - \hat{Y}_t)$$

Bet on b : $\frac{I_{a_t=b}}{p_t(b)} - \frac{I_{a_t=\hat{a}_t}}{p_t(\hat{a}_t)}$
--

- Macau keeps the mean correct
- We would also high probability statements
- So, we need $p_t(b)$ to not be too small
 - Easy math: $p_t(b) \geq t^{-1/3}$, but not optimal rates of convergence
 - Giving up a log: $p_t(b) \geq t^{-1/2}$. But, as $\hat{Y}_t(b)$ gets closer to $\hat{Y}_t(\hat{a}_t)$ we sample more often. On a log scale, this means we need $k \log(T)$ features.
 - Note: the fixed point solution will generate some randomization above and beyond that given by the lower bounds
- Similar behavior to UCB, but a different philosophy to justify it.

Bet: Contextual Bandits (vector version)

First we observe $X_t \in \mathcal{R}^d$, then we play an arm a_t and observe its outcome (vector version: $[Y_t]_i = \frac{r_t I_{a_t=i}}{p(a_t=i)}$):

- Forecast: $\hat{Y}_t = X_t \beta_{t-1}$, with $\beta \in \mathcal{R}^{d \times k}$ $\hat{Y}_t \in \mathcal{R}^k$.
- Strategy: Pick arm with highest forecast ($\hat{a}_t = \arg \max_j [\hat{Y}_t]_j$).
- Worry: Using some other β^* might be better.
- Naive Macau bet ($\hat{a}_t \rightarrow b$):

$$(I_{X_t(\beta_b^* - \beta_{\hat{a}_t}^*) > 0} - e_{\hat{a}_t}) \cdot (Y_t - \hat{Y}_t)$$

- These are hard to put in a linear space. But, given the low dimension (VC= $d + 2$) hope spring eternal.

Bet on b : $(e_b - e_{\hat{a}_t})$

Bet: Continuous action for contextual Bandits

First we observe $X_t \in \mathbb{R}^d$, then we play an action $a_t \in \mathcal{A} \subset \mathbb{R}^k$ and observe its outcome. (We'll actually penalize a quadratically and hence avoid the set \mathcal{A} .)

- Forecast: $\hat{Y}_t(a) = X_t^\top \beta_{t-1} a - a^\top a / 2$, with $\beta \in \mathbb{R}^{d \times k}$ and $\hat{Y}_t(a) \in \mathbb{R}^k$.
- Strategy: Pick “best” action: $\hat{a}_t = \arg \max_{a \in \mathcal{A}} \hat{Y}_t(a) = X_t^\top \hat{\beta}_{t-1}$.
- Worry: Using some other β^* might be better.
- Naive Macau bet ($\hat{a}_t \rightarrow (1 - \epsilon)\hat{a}_t + \epsilon X_t^\top \beta^*$):

$$(X_t^\top \beta^* - X_t^\top \hat{\beta}_t) \cdot (a_t - \hat{a}_t)(Y_t(a_t) - \hat{Y}_t(a_t))$$

Bet in direction $X_t^\top \beta^*$: (fillin)

Reinforcement Learning

The RL value function:

$$V_t^* = \max_{\pi} E \left(\sum_{i=t}^{\infty} \gamma^{i-t} r_i(\mathbf{a}_i^{\pi}) \middle| \mathcal{F}_t \right)$$

(γ is discount rate.) Recursively:

$$V_t^* = E (r_t(\mathbf{a}) + \gamma V_{t+1}^* | \mathcal{F}_t)$$

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The RL value function:

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(γ is discount rate.) Recursively:

$$V_t^* = E (r_t(\mathbf{a}) + \gamma V_{t+1}^* | \mathcal{F}_t)$$

V^* is a Y-variable and an X-variable!